

# **Unsupervised Learning**

## **Propagation on Factor Graphs**

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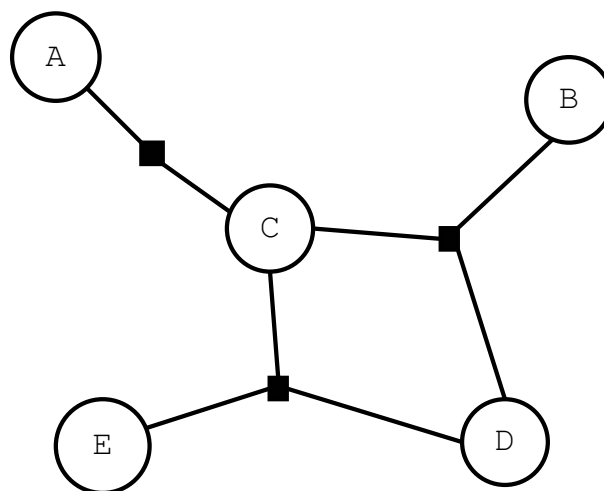
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# Factor Graphs

In a factor graph, the joint probability distribution is written as a product of factors. Consider a vector of variables  $\mathbf{x} = (x_1, \dots, x_n)$

$$p(\mathbf{x}) = p(x_1, \dots, x_n) = \frac{1}{Z} \prod_j f_j(\mathbf{x}_{S_j})$$

where  $Z$  is the normalisation constant,  $S_j$  denotes the subset of  $\{1, \dots, n\}$  which participate in factor  $f_j$  and  $\mathbf{x}_{S_j} = \{x_i : i \in S_j\}$ .



**variables nodes:** we draw open circles for each variable  $x_i$  in the distribution.

**function nodes:** we draw filled dots for each function  $f_j$  in the distribution.

# Propagation in Factor Graphs

Let  $n(x)$  denote the set of function nodes that are neighbors of  $x$ .

Let  $n(f)$  denote the set of variable nodes that are neighbors of  $f$ .

We can compute probabilities in a factor graph by propagating messages from variable nodes to function nodes and viceversa.

**message from variable  $x$  to local function  $f$ :**

$$\mu_{x \rightarrow f}(x) = \prod_{h \in n(x) \setminus \{f\}} \mu_{h \rightarrow x}(x)$$

**message from local function  $f$  to variable  $x$ :**

$$\mu_{f \rightarrow x}(x) = \sum_{\mathbf{x} \setminus x} \left( f(\mathbf{x}) \prod_{y \in n(f) \setminus \{x\}} \mu_{y \rightarrow f}(y) \right)$$

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$$\mu_{f \rightarrow x}(x) = \sum_{\mathbf{x} \setminus x} \left( f(\mathbf{x}) \prod_{y \in n(f) \setminus \{x\}} \mu_{y \rightarrow f}(y) \right)$$

Once a variable has received all messages from its neighboring function nodes we can compute the probability of that variable by multiplying all the messages and renormalising:

$$p(x) \propto \prod_{h \in n(x)} \mu_{h \rightarrow x}(x)$$

# Elimination Rules for Factor Graphs

- **eliminating observed variables**

If a variable  $x_i$  is **observed**, i.e. its value is given, then it is a *constant* in all functions that include  $x_i$ .

We can **eliminate**  $x_i$  from the graph by removing the corresponding node and modifying all neighboring functions to treat it as a constant.

# Elimination Rules for Factor Graphs

- **eliminating hidden variables**

If a variable  $x_i$  is **hidden** and we are not interested in it we can eliminate it from the graph by summing over all its values.

$$\begin{aligned}\sum_{x_i} p(\mathbf{x}) &= \frac{1}{Z} \sum_{x_i} \prod_j f_j(\mathbf{x}_{S_j}) \\ &= \frac{1}{Z} \prod_{j \notin \mathbf{n}(x_i)} f_j(\mathbf{x}_{S_j}) \left( \sum_{x_i} \prod_{k \in \mathbf{n}(x_i)} f_k(\mathbf{x}_{S_k}) \right) \\ &= \frac{1}{Z} \prod_{j \notin \mathbf{n}(x_i)} f_j(\mathbf{x}_{S_j}) \quad f_{\text{new}}(\mathbf{x}_{S_{\text{new}}})\end{aligned}$$

where  $f_{\text{new}}(\mathbf{x}_{S_{\text{new}}}) = \sum_{x_i} \prod_{k \in \mathbf{n}(x_i)} f_k(\mathbf{x}_{S_k})$  and  $S_{\text{new}} = \bigcup_{k \in \mathbf{n}(x_i)} S_k \setminus \{i\}$ .

This causes all its neighboring function nodes to merge into one new function node.