## GP Marginal Likelihood and Hyperparameters

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October 18th, 2022

- We give an interpretation of the marginal likelihood in terms of
  - a data fit
  - a complexity penalty
- covariance functions can be parameterized using hyperparameters
- hyperparameters can be fit by optimizing the marginal likelihood
  - this is a form of model selection
- Occam's razor is automatic and avoids overfitting

Log marginal likelihood has a closed form

$$\log Z_{|\mathbf{y}|} = \log p(\mathbf{y}|\mathbf{x}, \mathcal{M}_{i}) = -\frac{1}{2}\mathbf{y}^{\top}[\mathbf{K} + \sigma_{n}^{2}\mathbf{I}]^{-1}\mathbf{y} - \frac{1}{2}\log|\mathbf{K} + \sigma_{n}^{2}\mathbf{I}| - \frac{n}{2}\log(2\pi)$$

and is the combination of a data fit term and complexity penalty. Occam's Razor is automatic.

## Hyperparameters: properties of covariance functions

The covariance function which we have seen before

$$k(x, x') = \exp(-\frac{1}{2}(x - x')^2),$$

encodes that f(x) and f(x') have large covariance if x is close to x', but it doesn't really quantify what is means by close to?

We can parameterize the covariance function using hyperparameters such as l, in

$$k(x, x') = \exp \left(-\frac{(x-x')^2}{2\ell^2}\right).$$

Learning in Gaussian process models involves finding

- the form of the covariance function, and
- any unknown (hyper-) parameters θ.

## Example: Fitting the length scale parameter

Parameterized covariance function:  $k(x, x') = v^2 \exp \left(-\frac{(x - x')^2}{2\ell^2}\right) + \sigma_{noise}^2 \delta_{xx'}$ .



**Characteristic Lengthscales** 

input, x

The mean posterior predictive function is plotted for 3 different length scales (the blue curve corresponds to optimizing the marginal likelihood). Notice, that an almost exact fit to the data can be achieved by reducing the length scale – but the marginal likelihood does not favour this!

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How can Bayes rule help find the right model complexity? Marginal likelihoods and Occam's Razor



## An illustrative analogous example

Imagine the simple task of fitting the variance,  $\sigma^2$ , of a zero-mean Gaussian to a set of n scalar observations.

